# Decidability questions for Cuntz-Krieger algebras and their underlying dynamics

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## Outline

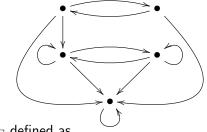


2 Graph  $C^*$ -algebras





## To a finite graph $E = (E_0, E_1, r, s)$ such as



we associate  $X_E$  defined as

$$\mathsf{X}_E = \{ (e_n) \in (E_0)^{\mathbb{Z}} \mid r(e_n) = s(e_{n+1}) \}$$

Note that  $X_E$  is closed in the topology of  $(E_0)^{\mathbb{Z}}$  and comes equipped with a shift map  $\sigma : X_E \to X_E$  which is a homeomorphism. We call  $X_E$  a **shift space** (of finite type) over the **alphabet**  $E_0$ .

### Definition

The suspension flow SX of a shift space X is  $X \times \mathbb{R}/\sim$  with

 $(x,t) \sim (\sigma(x), t-1)$ 

Note that SX has a canonical  $\mathbb{R}$ -action.

#### Definitions

Let X and Y be shift spaces.

- X is conjugate to Y (written  $X \simeq Y$ ) if there is a shift-invariant homeomorphism  $\varphi : X \to Y$ .
- X is flow equivalent to Y (written  $X \sim_{\rm FE} Y$ ) if there is an orientation-preserving homeomorphism  $\psi : SX \to SY$

#### Question

Are these notions decidable for shifts of finite type?

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### Theorem (Boyle-Steinberg)

Flow equivalence is decidable among shifts of finite type.

#### Definition

Let  $A \in M_n(\mathbb{Z}_+)$  and  $B \in M_m(\mathbb{Z}_+)$  be given. We say that A is elementary equivalent to B if there exist  $D \in M_{n \times m}(\mathbb{Z}_+)$  and  $E \in M_{m \times n}(\mathbb{Z}_+)$  so that

$$A = DE \qquad B = ED.$$

The smallest equivalence relation on  $\bigcup_{n\geq 1} M_n(\mathbb{Z}_+)$  is called strong shift equivalence.

Let  $G_A$  be the graph with adjacency matrix A. We abbreviate  $X_A = X_{G_A}$ .

Theorem (Williams)

 $X_A \simeq X_B$  if and only if A is strong shift equivalent to B.

### Definition

We say that that A and B are **shift equivalent** of lag  $\ell$  when there exist  $D \in M_{n \times m}(\mathbb{Z}_+)$  and  $E \in M_{m \times n}(\mathbb{Z}_+)$  so that

$$A^{\ell} = DE \qquad B^{\ell} = ED \qquad AD = DB \qquad EA = BE.$$

Strong shift equivalence implies shift equivalence.

#### Theorem (Kim-Roush)

Shift equivalence is decidable.

It took decades to disprove

William's conjecture

Shift equivalence coincides with strong shift equivalence.

and indeed it is a prominent open question if conjugacy is decidable for shifts of finite type.



## Shifts of finite type





## 4 Moves

## Singular and regular vertices

### Definitions

Let E be a graph and  $v \in E^0$ .

- v is a *sink* if  $|s^{-1}(\{v\})| = 0$
- v is an *infinite emitter* if  $|s^{-1}(\{v\})| = \infty$

### Definition

v is singular if v is a sink or an infinite emitter. v is regular if it is not singular.



## Graph algebras

#### Definition

The graph  $C^*$ -algebra  $C^*(E)$  is given as the universal  $C^*$ -algebra generated by mutually orthogonal projections  $\{p_v : v \in E^0\}$  and partial isometries  $\{s_e : e \in E^1\}$  with mutually orthogonal ranges subject to the Cuntz-Krieger relations

• 
$$s_e^* s_e = p_{r(e)}$$
  
•  $s_e s_e^* \le p_{s(e)}$   
•  $p_v = \sum_{s(e)=v} s_e s_e^*$  for every regular  $e$ 

 $C^*(E)$  is unital precisely when E has finitely many vertices.

#### Observation

$$\gamma_z(p_v) = p_v \qquad \gamma_z(s_e) = zs_e$$

induces a gauge action  $\mathbb{T} \mapsto \operatorname{Aut}(C^*(E))$ 

#### Definition

$$\mathfrak{D}_E = \overline{\operatorname{span}}\{s_\alpha s_\alpha^* \mid \alpha \text{ path of } E\}$$

Note that  $\mathfrak{D}_E$  is commutative and that

$$\mathfrak{D}_E \subseteq \mathfrak{F}_E = \{ a \in C^*(E) \mid \forall z \in \mathbb{T} : \gamma_z(a) = a \}$$

 $\mathfrak{D}_E$  has spectrum  $X_A$  when  $E = E_A$  arises from an essential and finite matrix A. This fundamental case was studied by Cuntz and Krieger, using the notation  $\mathcal{O}_A = C^*(E_A)$ .

### Theorem (E-Restorff-Ruiz-Sørensen)

\*-isomorphism and stable \*-isomorphism of unital graph  $C^*$ -algebras is decidable.

Theorem (Carlsen-E-Ortega-Restorff, Matsumoto-Matui)

 $(C^*(E_A)\otimes \mathbb{K},\mathfrak{D}\otimes c_0)\simeq (C^*(E_B)\otimes \mathbb{K},\mathfrak{D}\otimes c_0) \Longleftrightarrow \mathsf{X}_A\sim_{\mathrm{FE}}\mathsf{X}_B$ 

Theorem (Carlsen-Rout, Matsumoto)

 $(C^*(E_A) \otimes \mathbb{K}, \mathfrak{D} \otimes c_0, \gamma \otimes \mathrm{Id}) \simeq (C^*(E_B) \otimes \mathbb{K}, \mathfrak{D} \otimes c_0, \gamma \otimes \mathrm{Id})$   $\longleftrightarrow$   $\mathsf{X}_A \simeq \mathsf{X}_B$ 

### Theorem (E-Restorff-Ruiz-Sørensen)

\*-isomorphism and stable \*-isomorphism of Cuntz-Krieger algebras is decidable.

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Theorem (Carlsen-Rout, Matsumoto)

$$(\mathcal{O}_A \otimes \mathbb{K}, \mathfrak{D} \otimes c_0, \gamma \otimes \mathrm{Id}) \simeq (\mathcal{O}_B \otimes \mathbb{K}, \mathfrak{D} \otimes c_0, \gamma \otimes \mathrm{Id})$$

$$\longleftrightarrow$$

$$\mathsf{X}_A \simeq \mathsf{X}_B$$



## Shifts of finite type

2 Graph  $C^*$ -algebras





### Definition

With  $\mathsf{x},\mathsf{y},\mathsf{z}\in\{0,1\}$  we write

$$E \xrightarrow{xyz} F$$

when there exists a \*-isomorphism  $\varphi: C^*(E)\otimes \mathbb{K} \to C^*(F)\otimes \mathbb{K}$  with additionally satisfies

- $\varphi(1_{C^*(E)}\otimes e_{11})=1_{C^*(F)}\otimes e_{11}$  when  $\mathsf{x}=1$
- $\varphi \circ (\gamma \otimes \mathrm{Id}) = (\gamma \otimes \mathrm{Id}) \circ \varphi$  when y = 1
- $\varphi(\mathfrak{D}_E \otimes c_0) = \mathfrak{D}_F \otimes c_0$  when z = 1.

### Theorem (E-Restorff-Ruiz-Sørensen)

 $E \xrightarrow{\times 0z} F$  is decidable.

Theorem (Carlsen-E-Ortega-Restorff, Matsumoto-Matui)

$$E_A \xrightarrow{001} E_B \iff \mathsf{X}_A \sim_{\mathrm{FE}} \mathsf{X}_B$$

### Theorem (Carlsen-Rout, Matsumoto)

$$E_A \xrightarrow{011} E_B \iff \mathsf{X}_A \simeq \mathsf{X}_B$$



## Shifts of finite type

2 Graph  $C^*$ -algebras





## Moves



### Move (R)

#### Reduce a configuration with a transitional regular vertex, as



or

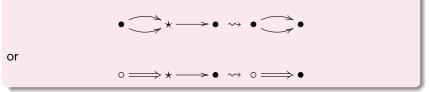






## Move (R)

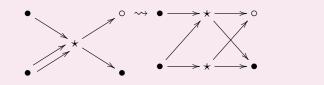
Reduce a configuration with a transitional regular vertex, as



## Moves

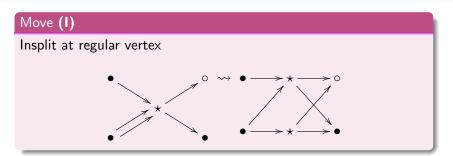
# Move (I)

### Insplit at regular vertex

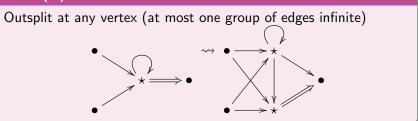


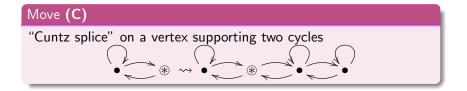
Move (O)

## Moves



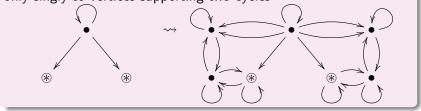
Move **(0)** 





## Move (P)

"Butterfly move" on a vertex supporting a single cycle emitting only singly to vertices supporting two cycles



## Theorem (E-Restorff-Ruiz-Sørensen)

Let  $C^{\ast}(E)$  and  $C^{\ast}(F)$  be unital graph algebras. Then the following are equivalent

(i)  $C^*(E) \otimes \mathbb{K} \simeq C^*(F) \otimes \mathbb{K}$ 

(ii) There is a finite sequence of moves of type(S),(R),(O),(I),(C),(P)

and their inverses, leading from E to F.