

The classification problem for Cuntz-Krieger algebras

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Content

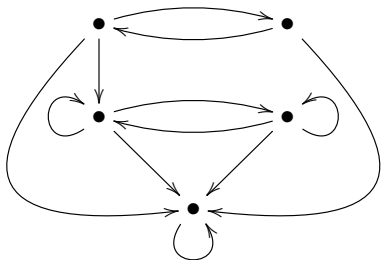
- 1 The geometric classification problem
- 2 Ideals and K -theory
- 3 Cuntz splice
- 4 Butterfly move

Outline

- 1 The geometric classification problem
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Throughout we let $A \in M_n(\mathbb{N}_0)$ be **essential**: no zero rows, no zero columns. We consider A as the adjacency matrix of a graph G_A .

$$\begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$



Cuntz-Krieger algebras

Definition

\mathcal{O}_A is the universal C^* -algebra generated by mutually orthogonal projections $\{p_v : v \in V(G_A)\}$ and partial isometries $\{s_e : e \in E(G_A)\}$ with mutually orthogonal ranges, subject to

- 1 $s_e^* s_e = p_{r(e)}$
- 2 $p_v = \sum_{s(e)=v} s_e s_e^*$

Key observations

- $K_0(\mathcal{O}_A) = \text{coker}(A^t - I)$ and $K_1(\mathcal{O}_A) = \ker(A^t - I)$
- $S_i \mapsto \lambda S_i$ induces a gauge action $\mathbb{T} \mapsto \text{Aut}(\mathcal{O}_A)$
- $\mathcal{O}_{[1]} = C(\mathbb{T})$, $\mathcal{O}_{\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}} = M_2(C(\mathbb{T}))$ etc.

Geometric classification problem

Describe the equivalence relation on graphs defined by

$$G_A \sim_{C^*} G_B \iff \mathcal{O}_A \otimes \mathbb{K} \simeq \mathcal{O}_B \otimes \mathbb{K}$$

Symbolic dynamics

Definition

Let \mathfrak{a} be a finite set. A **shift space** over \mathfrak{a} is a subset of $\mathfrak{a}^{\mathbb{Z}}$ which is closed (product topology) and shift invariant.

Edge shift

$$X_A = \{(e_n) \in E(G_A) \mid r(e_n) = s(e_{n+1})\}$$

Definition

The **suspension flow** SX of a shift space X is $X \times \mathbb{R} / \sim$ with

$$(x, t) \sim (\sigma(x), t - 1)$$

Note that SX has a canonical \mathbb{R} -action.

Definitions

Let X and Y be shift spaces.

- X is conjugate to Y (written $X \simeq Y$) if there is a shift-invariant homeomorphism $\varphi : X \rightarrow Y$.
- X is flow equivalent to Y (written $X \sim_{\text{FE}} Y$) if there is an orientation-preserving homeomorphism $\psi : SX \rightarrow SY$

Theorem (Cuntz/Krieger)

$$X_A \sim_{\text{FE}} X_B \implies \mathcal{O}_A \otimes \mathbb{K} \simeq \mathcal{O}_B \otimes \mathbb{K}$$

Moves

Move (I)

Insplit at any vertex, e.g.



Move (O)

Outsplit at any vertex, e.g.



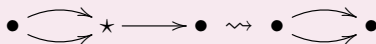
Theorem (Williams)

The following are equivalent

- ① $X_A \simeq X_B$
- ② G_A can be obtained from G_B by a finite number of moves of type **(I)** and **(O)**, and their inverses.

Move (R)

Reduce a configuration with a transitional vertex, e.g.

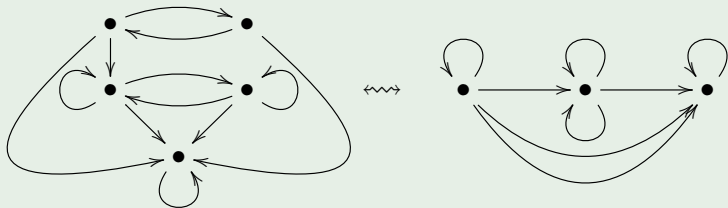


Theorem (Parry/Sullivan)

The following are equivalent

- ① $X_A \sim_{\text{FE}} X_B$
- ② G_A can be obtained from G_B by a finite number of moves of type **(I)**, **(O)**, and **(R)**, and their inverses.

Example



Conclusion

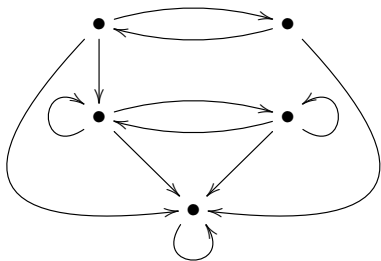
When G_A can be obtained from G_B by a finite number of moves of type **(I)**, **(O)**, and **(R)**, and their inverses, we have that $G_A \sim_{C^*} G_B$.

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The gauge invariant ideals of \mathcal{O}_A can be determined directly from a block structure of A with irreducible diagonal blocks.

$$\left[\begin{array}{cc|ccc} 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 & 1 \\ \hline 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 & 1 \\ \hline 0 & 0 & 0 & 0 & 1 \end{array} \right]$$



Cuntz' condition (II)

The following are equivalent

- 1 No irreducible block of A is a permutation matrix
- 2 All ideals of \mathcal{O}_A are gauge invariant
- 3 \mathcal{O}_A has a finite number of ideals

Theorem (Rørdam 1995)

The K_0 -group $K_0(\mathcal{O}_A)$ is a complete invariant for stable isomorphism of simple Cuntz-Krieger algebras.

Theorem (Rørdam 1997)

The six-term exact sequence

$$\begin{array}{ccccc}
 K_0(\mathfrak{I}) & \longrightarrow & K_0(\mathcal{O}_A) & \longrightarrow & K_0(\mathcal{O}_A/\mathfrak{I}) \\
 \uparrow & & & & \downarrow \\
 K_1(\mathcal{O}_A/\mathfrak{I}) & \longleftarrow & K_1(\mathcal{O}_A) & \longleftarrow & K_1(\mathfrak{I})
 \end{array}$$

is a complete invariant for stable isomorphism of Cuntz-Krieger algebras with a unique non-trivial ideal \mathfrak{I} .

Theorem (Restorff 2006)

The reduced filtered K -theory $\mathbf{FK}(-)$ consisting of certain partial strands of six-term exact sequences

$$K_1(\mathfrak{J}/\mathfrak{J}) \longrightarrow K_0(\mathfrak{K}/\mathfrak{J}) \longrightarrow K_0(\mathfrak{K}/\mathfrak{J}) \longrightarrow K_0(\mathfrak{J}/\mathfrak{J})$$

arising from a selection of ideals

$$\mathfrak{J} \triangleleft \mathfrak{J} \triangleleft \mathfrak{K} \triangleleft \mathcal{O}_A$$

is a complete invariant for stable isomorphism of Cuntz-Krieger algebras with condition (II).

Example

With

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

we have

$$K_0(\mathcal{O}_A) = \mathbb{Z} = K_0(\mathcal{O}_{[1]})$$

but

$$K_0(\mathcal{O}_A)_+ = \mathbb{Z} \neq \mathbb{N}_0 = K_0(\mathcal{O}_{[1]})_+$$

Observation

The **ordered** K_0 -group $K_0(\mathcal{O}_A)$ is a complete invariant for stable isomorphism of **gauge** simple Cuntz-Krieger algebras.

Theorem (E-Restorff-Ruiz-Sørensen)

The **ordered** reduced filtered K -theory $\mathbf{FK}^{+, \gamma}(-)$ remains a complete invariant for stable isomorphism of Cuntz-Krieger algebras satisfying one of the conditions

- The C^* -algebra has at most one non-trivial gauge invariant ideal
- The matrix satisfies condition $(\neg II)$: Every irreducible component is a permutation matrix.

The order is trivial in the condition (II) case. The $(\neg II)$ case arises naturally in applications such as the quantum lens spaces of Hong/Szymański.

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Theorem (Rørdam 1995)

The following are equivalent when \mathcal{O}_A and \mathcal{O}_B are simple

- ① $\mathcal{O}_A \otimes \mathbb{K} \simeq \mathcal{O}_B \otimes \mathbb{K}$
- ② $K_0(\mathcal{O}_A) \simeq K_0(\mathcal{O}_B)$
- ③ X_A is flow equivalent to X_B or to $X_{B'}$ where

$$B' = \begin{bmatrix} b_{11} & \cdots & b_{1n} & 0 & 0 \\ \vdots & & \vdots & 0 & 0 \\ b_{n1} & \cdots & b_{nn} & 1 & 0 \\ 0 & \cdots & 1 & 1 & 1 \\ 0 & \cdots & 0 & 1 & 1 \end{bmatrix}$$

Cuntz had reduced ③ \implies ① to the case $A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$ by an argument we will generalize below.

Theorem (Matui-Matsumoto 2013)

The following are equivalent when \mathcal{O}_A and \mathcal{O}_B are simple

- ① $(\mathcal{O}_A \otimes \mathbb{K}, \mathcal{D}_A \otimes c_0) \simeq (\mathcal{O}_B \otimes \mathbb{K}, \mathcal{D}_B \otimes c_0)$
- ② $K_0(\mathcal{O}_A) \simeq K_0(\mathcal{O}_B)$ and $\det(I - A) = \det(I - B)$
- ③ X_A is flow equivalent to X_B
- ④ G_A can be obtained from G_B by a finite number of moves of type **(R)**, **(I)** and **(O)**, and their inverses.

Remark

In recent work by Carlsen/E/Ortega/Restorff we managed to find a different proof of the key component of Matsumoto/Matui which generalizes ① \iff ③ to any \mathcal{O}_A of type (II).

Move (C)

“Cuntz splice” on a vertex supporting two cycles



Geometric version of Rørdam's theorem

Theorem

The following are equivalent when \mathcal{O}_A and \mathcal{O}_B are simple

- 1 $\mathcal{O}_A \otimes \mathbb{K} \simeq \mathcal{O}_B \otimes \mathbb{K}$
- 2 $K_0(\mathcal{O}_A) \simeq K_0(\mathcal{O}_B)$
- 3 G_A can be obtained from G_B by a finite number of moves of type **(R)**, **(I)**, **(O)** and **(C)**, and their inverses.

Theorem (Restorff, E/Ruiz/Sørensen)

When A and B satisfy one of

- A and B have property (II)
- \mathcal{O}_A and \mathcal{O}_B each have at most one non-trivial gauge invariant ideal
- A and B have property $(\neg II)$

the following are equivalent

- 1 $\mathcal{O}_A \otimes \mathbb{K} \simeq \mathcal{O}_B \otimes \mathbb{K}$
- 2 $\mathbf{FK}^{+, \gamma}(\mathcal{O}_A) \simeq \mathbf{FK}^{+, \gamma}(\mathcal{O}_B)$
- 3 G_A can be obtained from G_B by a finite number of moves of type **(R)**, **(I)**, **(O)** and **(C)**, and their inverses.

Example

The pair of matrices

$$\begin{bmatrix} 0 & 1 & 0 & 0 & \mathbf{1} \\ 1 & 0 & 1 & 0 & \mathbf{1} \\ 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \quad \begin{bmatrix} 0 & 1 & 0 & 0 & \mathbf{0} \\ 1 & 0 & 1 & 0 & \mathbf{0} \\ 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

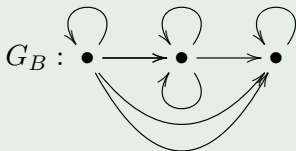
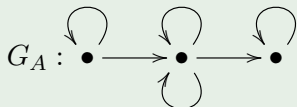
is not covered by the previous result.

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Example (E-Restorff-Ruiz-Sørensen)

When



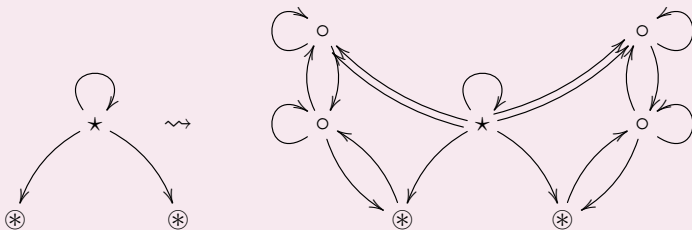
we get that

$$\mathcal{O}_A \otimes \mathbb{K} \simeq \mathcal{O}_B \otimes \mathbb{K},$$

yet G_A can not be obtained from G_B by a finite number of moves of type **(R)**, **(I)**, **(O)** and **(C)**, or their inverses.

Move (P)

“Pulelehua move” on a vertex supporting a single cycle emitting only singly to vertices supporting two cycles



Theorem (E/Restorff/Ruiz/Sørensen)

The following are equivalent

- 1 $\mathcal{O}_A \otimes \mathbb{K} \simeq \mathcal{O}_B \otimes \mathbb{K}$
- 2 $\mathbf{FK}^{+, \gamma}(\mathcal{O}_A) \simeq \mathbf{FK}^{+, \gamma}(\mathcal{O}_B)$
- 3 G_A can be obtained from G_B by a finite number of moves of type **(R)**, **(I)**, **(O)**, **(C)** and **(P)**, and their inverses.

- Isomorphism is decidable due to of recent results by Boyle/Steinberg.
- The geometric classification results extend to all unital graph algebras.
- The classification is strong and thus leads to exact classification by taking the class of the unit into account.
- By entirely different methods, a complete classification for purely infinite graph algebras with finitely many ideals has been obtained by Bentmann/Meyer.
- No list of moves is known to generate stable isomorphism even for simple (nonunital!) graph algebras.
- There exist two graph algebras each with two non-trivial ideals for which the classification problem is open.