

A NOTE ON STOCHASTIC BURGERS' SYSTEM OF EQUATIONS

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ABSTRACT

We consider a stochastic version of a system of two equations formulated by Burgers in [2] with the aim to describe the laminar and turbulent motions of a fluid in a channel. The existence and uniqueness theorem for a global solution is established. The paper generalizes the result from the paper [11] by Da Prato and Gałtarek dealing with the equation describing only the turbulent motion.

1 Introduction

The paper is concerned with the stochastic version of two hydrodynamic equations for the turbulent flow in a channel between parallel walls. The original non-stochastic model was first proposed by Burgers in [2]. The system is derived from the theory of turbulent fluid motion and has similar properties as the Navier-Stokes equation, but is simpler to study.

Let $U = U(t)$ denote the *primary* velocity of the fluid, parallel to the walls of the channel, whereas the second one $v = v(t, x)$ denote the *secondary* velocity of the turbulent motion. Let P , ρ and μ be constants representing, respectively, an exterior force, analogous to the mean pressure gradient in the hydrodynamic case, the density of the fluid and its viscosity. Set $\nu = \frac{\mu}{\rho} > 0$.

According to [2], the functions $U(t)$, $v(t, \cdot)$, $t \geq 0$, should satisfy the following system of equations

$$\frac{dU(t)}{dt} = P - \nu U(t) - \int_0^1 v^2(t, x) dx \quad \text{for } t > 0, \quad (1)$$

$$\frac{\partial v(t, x)}{\partial t} = \nu \frac{\partial^2 v(t, x)}{\partial x^2} + U(t) v(t, x) - \frac{\partial}{\partial x} (v^2(t, x)) \quad (2)$$

with the initial and boundary conditions

$$U(0) = U_0, \quad v(0, x) = v_0(x), \quad v(t, 0) = v(t, 1) = 0, \quad x \in (0, 1), \quad t > 0. \quad (3)$$

The simplified version consisting of one equation on v only ($U(t) \equiv 0$), $t \geq 0$,

$$\frac{\partial v(t, x)}{\partial t} = \nu \frac{\partial^2 v(t, x)}{\partial x^2} - \frac{\partial}{\partial x} (v^2(t, x)) \quad (4)$$

with the initial and boundary conditions

$$v(0, x) = v_0(x), \quad v(t, 0) = v(t, 1) = 0 \quad (5)$$

for $x \in (0, 1)$ and for $t > 0$, was investigated by many authors, e.g., in [20] and [25]. For the stochastic version of such equation see e.g. to the papers [7], [8], [10], [18], [21] and [23].

The system (1)-(3) was analysed in [2] and [3]. The existence and uniqueness theorem for the global solution of the system was examined by Dłotko in [9], using the Galerkin method. Other properties of such systems were studied by Cholewa and Dłotko in [5].

The Burger's system (1)-(3) as well as the Burger's equation do not display any chaotic phenomena and therefore a stochastic perturbations of (4) was proposed as a better model, see [4], [6], [19].

The stochastic Burgers' equation is of the form

$$\frac{\partial v(t, x)}{\partial t} = \nu \frac{\partial^2 v(t, x)}{\partial x^2} - \frac{\partial}{\partial x} (v^2(t, x)) + g(v(t, x)) \frac{\partial^2 B(t, x)}{\partial t \partial x} \quad (6)$$

with the initial and boundary conditions (5), where B is a Brownian sheet on $[0, \infty) \times (0, 1)$ and $\frac{\partial^2 B(t, x)}{\partial t \partial x}$ is the time-space white noise.

The existence and uniqueness theorem for (6) with additive noise $g \equiv 1$ was established in [12] and the case of general g , in [11].

Our paper generalizes the existence and uniqueness result from [11] to the system

$$\frac{dU(t)}{dt} = P - \nu U(t) - \int_0^1 v^2(t, x) dx \quad \text{for } t > 0, \quad (7)$$

$$\begin{aligned} \frac{\partial v(t, x)}{\partial t} &= \nu \frac{\partial^2 v(t, x)}{\partial x^2} + U(t) v(t, x) \\ &\quad - \frac{\partial}{\partial x} (v^2(t, x)) + g(v(t, x)) \frac{\partial^2 B(t, x)}{\partial t \partial x} \end{aligned} \quad (8)$$

with the initial and boundary conditions (3). We adapt the method from [11]. We prove first the existence of a local solution by proper modification of the drift terms and Banach fixed point argument and then we establish a priori estimates to get global existence.

2 Preliminaries and formulation of the main result

Let $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \in [0, T]}, P)$ be a filtered probability space on which an increasing and right-continuous family $(\mathcal{F}_t)_{t \in [0, T]}$ of sub- σ -algebras of \mathcal{F} is defined such that \mathcal{F}_0 contains all P-null sets in \mathcal{F} . We model mathematically the space-time white noise B as the distributional derivative of the cylindrical Wiener process W

$$W(t) = \sum_{k=1}^{\infty} W_k(t) e_k. \quad (9)$$

Here (e_k) is an orthonormal basis of $L^2 = L^2(0, 1)$,

$$e_k(x) = \sqrt{\frac{2}{\pi}} \sin k\pi x, \quad x \in (0, 1), \quad k = 1, 2, \dots \quad (10)$$

The scalar product in L^2 is denoted by (\cdot, \cdot) ,

$$(h, \psi) = \int_0^1 h(x) \psi(x) dx$$

and the norm by $\|\cdot\|$.

We consider the following stochastic one-dimensional Burgers' problem

$$\frac{dU(t)}{dt} = P - \nu U(t) - \int_0^1 v^2(t, x) dx \quad \text{for } t > 0, \quad (11)$$

$$\begin{aligned} \frac{\partial v(t, x)}{\partial t} &= \nu \frac{\partial^2 v(t, x)}{\partial x^2} + U(t) v(t, x) \\ &\quad - \frac{\partial}{\partial x} (v^2(t, x)) + g(v(t, x)) \frac{\partial W(t)}{\partial t} \end{aligned} \quad \text{for} \quad (12)$$

with the initial and boundary conditions

$$\begin{aligned} U(0) &= U_0, \\ v(0, x) &= v_0(x) \quad \text{for } x \in (0, 1), \\ v(t, 0) &= v(t, 1) = 0 \quad \text{for } t > 0. \end{aligned} \quad (13)$$

We assume that g is a real valued Lipschitz continuous and bounded function.

Notice that if we replace v by $-u$ in (12), then we obtain an equivalent form of equation (12) with the positive sign before $\frac{\partial}{\partial x} (v^2(t, x))$.

We have the following definition

Definition 1 A pair of processes $\left(\begin{matrix} U \\ v \end{matrix} \right)$ is a weak solution to problem (11)-(13) if and only if $U(t)$, $t \geq 0$, and $v(t)$, $t \geq 0$, are adapted continuous processes with values in \mathbb{R}^1 and L^2 , respectively, $U(0) = U_0$, $v(0) = v_0$ and :

(i) for arbitrary $t \geq 0$:

$$U(t) = U_0 + tP - \nu \int_0^t U(s) ds - \int_0^t \|v(s)\|^2 ds, \quad P\text{-a.s.}, \quad (14)$$

(ii) for arbitrary $t \geq 0$ and arbitrary $\varphi \in C_0^\infty(0, 1)$:

$$\begin{aligned} (v(t), \varphi) &= (v_0, \varphi) + \int_0^t U(s) (v(s), \varphi) ds \\ &\quad + \int_0^t (v(s), \nu \frac{\partial^2}{\partial x^2} \varphi) ds + \int_0^t (v^2(s), \frac{\partial}{\partial x} \varphi) ds \\ &\quad + \int_0^t (\varphi, g(v(s)) dW(s)), \quad P\text{-a.s.} \end{aligned} \quad (15)$$

Notice that from the very definition of the distributional derivative $\frac{\partial}{\partial x}v^2$, for arbitrary $v \in L^2$:

$$\left(\frac{\partial}{\partial x}v^2, \varphi\right) = - \int_0^t v^2(x) \frac{\partial}{\partial x} \varphi(x) ds = -(v^2, \frac{\partial}{\partial x} \varphi).$$

We introduce now an equivalent concept of the *integral solution*. Let $S(t)$, $t \geq 0$, be the classical heat semigroup on L^2 . Then, for $v \in L^2$:

$$S(t)v = \sum_{k=1}^{\infty} e^{-\frac{\pi^2}{\nu}k^2t} (v, e_k) e_k \quad (16)$$

with the convergence of the series in L^2 . It is well known that the generator A of the semigroup $S(t)$, $t \geq 0$, is identical with the second derivative operator $\frac{\partial^2}{\partial x^2}$ on the domain $D(A)$ consisting of functions v such that $v, \frac{\partial v}{\partial x}$ are absolutely continuous with $\frac{\partial^2 v}{\partial x^2} \in L^2$, $v(0) = v(1) = 0$. In some places $S(t)$, $t \geq 0$, will be denoted by e^{At} , $t \geq 0$.

We need the following lemma with the proof postponed to Appendix.

Lemma 1 *The operator $S(t)$, $t \geq 0$, can be extended linearly to the space of all distributions of the form $\frac{\partial}{\partial x}v$, $v \in L^1(0, 1)$, in such a way that it takes values in L^2 and*

$$\| S(t) \frac{\partial}{\partial x} v \| \leq \| v \|_{L^1(0,1)} \left(\sum_{k=1}^{\infty} \frac{2\pi}{\sqrt{\nu}} k^2 e^{-\frac{2\pi^2}{\nu}k^2t} \right)^{1/2}. \quad (17)$$

Definition 2 *A pair of continuous adapted processes $\begin{pmatrix} U \\ v \end{pmatrix}$ with values in \mathbb{R}^1 and L^2 , respectively, is said to be an integral solution to problem (11)-(13) if*

$$U(t) = e^{-\nu t} U_0 + \int_0^t e^{-\nu(t-s)} (P - \|v(s)\|^2) ds \quad (18)$$

and

$$\begin{aligned} v(t) = & S(t)v_0 + \int_0^t S(t-s)U(s)v(s)ds \\ & + \int_0^t S(t-s) \frac{\partial}{\partial x} v^2(s) ds + \int_0^t S(t-s)g(v(s))dW(s). \end{aligned} \quad (19)$$

In the integral

$$\int_0^t S(t-s) \frac{\partial}{\partial x} v^2(s) ds, \quad t > 0$$

we use the extension of the operator $S(t-s)$ described in Lemma 1.

We have the following result which proof can be found for instance in [24].

Proposition 2 *A continuous adapted process $\begin{pmatrix} U \\ v \end{pmatrix}$ is an integral solution to problem (11)-(13) if and only if it is a weak solution to problem (11)-(13).*

The main result of the paper is contained in the following

Theorem 3 *System (11)-(13) has a unique weak solution.*

The proof is given in the following sections.

3 Existence of a local solution

Let $\pi_{n,1} : \mathbb{R}^1 \rightarrow B_1(0, n)$ be the projection onto the interval $B_1(0, n) = \{U \in \mathbb{R}^1 : |U| \leq n\}$ and let $\pi_{n,2} : L^2 \rightarrow B_2(0, n)$ be the projection onto the ball $B_2(0, n) = \{v \in L^2 : \|v\| \leq n\}$, where

$$\pi_{n,1}(U) = \begin{cases} U & \text{if } |U| \leq n, \\ \frac{nU}{|U|} & \text{if } |U| > n. \end{cases} \quad (20)$$

and

$$\pi_{n,2}(v) = \begin{cases} v & \text{if } \|v\| \leq n, \\ \frac{nv}{\|v\|} & \text{if } \|v\| > n. \end{cases} \quad (21)$$

Let Z_T^p , $p > 1$, denote the space of all continuous adapted processes $X(t) = \begin{pmatrix} U(t) \\ v(t) \end{pmatrix}$ on $[0, T]$ with values on $\mathbb{R}^1 \times L^2$ such that

$$\begin{aligned} \|X\|_{Z_T^p} &= \left\| \begin{pmatrix} U \\ v \end{pmatrix} \right\|_T \\ &= (E(\sup_{t \in [0, T]} |U(t)|^p))^{1/p} + (E(\sup_{t \in [0, T]} \|v(t)\|^p))^{1/p} < \infty \end{aligned} \quad (22)$$

with fixed initial conditions $U(0) = U_0$, $v(0) = v_0$. We define

$$\| \begin{pmatrix} U \\ v \end{pmatrix} \|_T = \| U \|_{1,T} + \| v \|_{2,T}. \quad (23)$$

Now we prove

Proposition 4 *For arbitrary $p > 4$ and each $n = 1, 2, \dots$ the following system of equations*

$$U(t) = e^{-\nu t} U_0 + \int_0^t e^{-\nu(t-s)} (P - \| \pi_{n,2} v(s) \|^2) ds \quad (24)$$

and

$$\begin{aligned} v(t) &= S(t)v_0 + \int_0^t S(t-s) \pi_{n,1} U(s) \pi_{n,2} v(s) ds \\ &+ \int_0^t S(t-s) \frac{\partial}{\partial x} (\pi_{n,2} v(s))^2 ds + \int_0^t S(t-s) g(v(s)) dW(s), \\ &t \in [0, T] \end{aligned} \quad (25)$$

has a unique weak solution in the space Z_T^p .

Let us stress that we look for a continuous and adapted process $v(s)$, $s \geq 0$, with values in L^2 , and such that $\frac{\partial}{\partial x} (\pi_{n,2} v(s))^2$ is the derivative in the distribution theory sense (on the interval $(0, 1)$) of the function belonging to $L^1(0, 1)$ (because $(\pi_{n,2} v(s))^2 \in L^1(0, 1)$). From Lemma 1 we have that S can be extended to the derivatives of the functions from $L^1(0, 1)$. Therefore, equation (25) has a clear meaning.

Proof of Proposition 4. We introduce nonlinear operators F_n , G , H_n and I_n acting on processes $U(t)$, $t \geq 0$, and $v(t)$, $t \geq 0$, according to the following formulae:

$$\begin{aligned} F_n(U, v)(t) &= e^{-\nu t} U_0 + \int_0^t e^{-\nu(t-s)} (P - \| \pi_{n,2} v(s) \|^2) ds \\ &= e^{-\nu t} U_0 + \frac{1 - e^{-\nu t}}{\nu} P - \int_0^t e^{-\nu(t-s)} \| \pi_{n,2} v(s) \|^2 ds, \end{aligned} \quad (26)$$

$$G(U, v)(t) = \int_0^t S(t-s) g(v(s)) dW(s), \quad (27)$$

$$H_n(U, v)(t) = \int_0^t S(t-s) \frac{\partial}{\partial x} (\pi_{n,2} v(s))^2 ds \quad (28)$$

and

$$I_n(U, v)(t) = S(t)v_0 + \int_0^t S(t-s) \pi_{n,1} U(s) \pi_{n,2} v(s) ds. \quad (29)$$

Observe that system (24)-(25) is equivalent to fixed point problem:

$$U = F_n(U, v), \quad (30)$$

$$v = G(U, v) + H_n(U, v) + I_n(U, v). \quad (31)$$

We shall show that for arbitrary n the mapping

$$\begin{pmatrix} U \\ v \end{pmatrix} \rightarrow \begin{pmatrix} F_n(U, v) \\ G(U, v) + H_n(U, v) + I_n(U, v) \end{pmatrix} \quad (32)$$

is a contraction in the space $Z_{T_n}^p$, for properly chosen T_n . Therefore, system (30)-(31) has a unique solution on the interval $[0, T_n]$. By the standard iteration procedure system (30)-(31) has a unique global solution denoted by $\begin{pmatrix} U_n \\ v_n \end{pmatrix}$.

First we shall show that for each $n = 1, 2, \dots$ and $T > 0$ there exists a constant $C_{T,n}$ such that for $X = \begin{pmatrix} U \\ v \end{pmatrix}$, $\bar{X} = \begin{pmatrix} \bar{U} \\ \bar{v} \end{pmatrix} \in Z_T^p$:

$$\begin{aligned} & \left\| \begin{pmatrix} F_n(U, v) \\ G(U, v) + H_n(U, v) + I_n(U, v) \end{pmatrix} - \begin{pmatrix} F_n(\bar{U}, \bar{v}) \\ G(\bar{U}, \bar{v}) + H(\bar{U}, \bar{v}) + I_n(\bar{U}, \bar{v}) \end{pmatrix} \right\|_T \\ & \leq C_{T,n} \left\| \begin{pmatrix} U \\ v \end{pmatrix} - \begin{pmatrix} \bar{U} \\ \bar{v} \end{pmatrix} \right\|_T. \end{aligned} \quad (33)$$

We have from (23):

$$\begin{aligned} & \left\| \begin{pmatrix} F_n(U, v) \\ G(U, v) + H_n(U, v) + I_n(U, v) \end{pmatrix} - \begin{pmatrix} F_n(\bar{U}, \bar{v}) \\ G(\bar{U}, \bar{v}) + H(\bar{U}, \bar{v}) + I_n(\bar{U}, \bar{v}) \end{pmatrix} \right\|_T \\ & = \left\| F_n(U, v) - F_n(\bar{U}, \bar{v}) \right\|_{1,T} \\ & + \left\| (G(U, v) + H_n(U, v) + I_n(U, v)) - (G(\bar{U}, \bar{v}) + H(\bar{U}, \bar{v}) + I_n(\bar{U}, \bar{v})) \right\|_{2,T}. \end{aligned} \quad (34)$$

Step 1⁰. First we consider

$$\begin{aligned} & F_n(U, v)(t) - F_n(\bar{U}, \bar{v})(t) \\ &= \int_0^t e^{-\nu(t-s)} [\| \pi_{n,2} v(s) \|^2 - \| \pi_{n,2} \bar{v}(s) \|^2] ds. \end{aligned}$$

We shall find a constant $C_{T,n}^1$ such that

$$\| F_n(U, v) - F_n(\bar{U}, \bar{v}) \|_{1,T} \leq C_{T,n}^1 \| \begin{pmatrix} U \\ v \end{pmatrix} - \begin{pmatrix} \bar{U} \\ \bar{v} \end{pmatrix} \|_T. \quad (35)$$

Since $\nu > 0$ and

$$\| \| \pi_n a \| - \| \pi_n b \| \| \leq \| a - b \|, \quad a, b \in L^2,$$

therefore,

$$\begin{aligned} & | F_n(U, v)(t) - F_n(\bar{U}, \bar{v})(t) | \\ & \leq \int_0^t e^{-\nu(t-s)} | \| \pi_{n,2} v(s) \|^2 - \| \pi_{n,2} \bar{v}(s) \|^2 | ds \\ & = \int_0^t e^{-\nu(t-s)} | (\| \pi_{n,2} v(s) \| \\ & - \| \pi_{n,2} \bar{v}(s) \|) (\| \pi_{n,2} v(s) \| + \| \pi_{n,2} \bar{v}(s) \|) | ds \\ & \leq 2n \int_0^t e^{-\nu(t-s)} | \| \pi_{n,2} v(s) \| - \| \pi_{n,2} \bar{v}(s) \| | ds \\ & \leq 2n \int_0^t \| v(s) - \bar{v}(s) \| ds. \end{aligned}$$

From the Hölder inequality, if $q = \frac{p}{p-1}$, we have

$$\begin{aligned} & E(\sup_{t \in [0, T]} (2n \int_0^t \| v(s) - \bar{v}(s) \| ds)^p) \\ & \leq (2n)^p E[(\int_0^T \| v(s) - \bar{v}(s) \| ds)^p] \\ & \leq (2n)^p E(\int_0^T \| v(s) - \bar{v}(s) \|^p ds) (\int_0^T ds)^{\frac{p}{q}} \\ & \leq (2n)^p T^p E(\sup_{s \leq T} \| v(t) - \bar{v}(t) \|^p). \end{aligned}$$

Hence

$$\begin{aligned}
& \| F_n(U, v) - F_n(\bar{U}, \bar{v}) \|_{1,T} \\
&= (E(\sup_{t \in [0, T]} | F_n(U, v)(t) - F_n(\bar{U}, \bar{v})(t) |^p))^{\frac{1}{p}} \\
&\leq 2nT \| v - \bar{v} \|_{2,T} .
\end{aligned}$$

So we can set

$$C_{T,n}^1 = 2nT. \quad (36)$$

To go further let us recall that, see (25),

$$\begin{aligned}
& I_n(U, v)(t) + H_n(U, v)(t) + G(U, v)(t) \\
&= S(t)v_0 + \int_0^t S(t-s)\pi_{n,1}U_n(s)\pi_{n,2}v_n(s)ds \\
&\quad + \int_0^t S(t-s)\frac{\partial}{\partial x}(\pi_{n,2}v(s))^2ds + \int_0^t S(t-s)g(v(s))dW(s).
\end{aligned}$$

Step 2⁰. We estimate now

$$\| G(U, v) - G(\bar{U}, \bar{v}) \|_{2,T} .$$

To treat the stochastic integral

$$\int_0^t S(t-s)[g(v(s)) - g(\bar{v}(s))]dW(s)$$

we use the factorization procedure similarly as in [26], [11] (see also [24]). Let us fix γ such that $\frac{1}{p} < \gamma < \frac{1}{4}$ and define on $L^p([0, T], L^2)$ for $t \in [0, T]$:

$$R_\gamma h(t) = \int_0^t (t-s)^{\gamma-1} e^{A(t-s)} h(s) ds,$$

$h \in L^p([0, T], L^2)$. Then for $t \in [0, T]$:

$$R_\gamma Y(t) = \int_0^t S(t-s)[g(v(s)) - g(\bar{v}(s))]dW(s)$$

where

$$Y(t) = \frac{\sin \pi\gamma}{\gamma} \int_0^t (t-s)^{-\gamma} e^{A(t-s)} [g(v(s)) - g(\bar{v}(s))] dW(s), \quad t \in [0, T].$$

By Hölder inequality, for $0 \leq t \leq T$, $h \in L^p([0, T], L^2)$

$$\| R_\gamma h(t) \| \leq \left(\frac{t^{(\gamma-1)q+1}}{(\gamma-1)q+1} \right)^{\frac{1}{q}} \| h \|_{L^p([0, T], L^2)}.$$

Therefore R_γ is a bounded operator from $L^p([0, T], L^2)$ to $C([0, T], L^2)$ and

$$\begin{aligned} \sup_{0 \leq t \leq T} \| R_\gamma h(t) \| &\leq \left(\frac{T^{(\gamma-1)q+1}}{(\gamma-1)q+1} \right)^{\frac{1}{q}} \| h \|_{L^p([0, T], L^2)} \\ &\leq \left(\frac{T^{(\gamma-1)\frac{p}{p-1}+1}}{(\gamma-1)\frac{p}{p-1}+1} \right)^{\frac{p-1}{p}} \| h \|_{L^p([0, T], L^2)}, \end{aligned}$$

where $\frac{1}{p} + \frac{1}{q} = 1$. So

$$\| R_\gamma \| \leq \left(\frac{T^{(\gamma-1)\frac{p}{p-1}+1}}{(\gamma-1)\frac{p}{p-1}+1} \right)^{\frac{p-1}{p}}. \quad (37)$$

Note that

$$(\gamma-1)\frac{p}{p-1} + 1 > 0.$$

We therefore have

$$\begin{aligned} E(\sup_{0 \leq t \leq T} \| G(U, v)(t) - G(\bar{U}, \bar{v})(t) \|^p) & \\ \leq \| R_\gamma \|^p E \| Y \|^p_{L^p([0, T], L^2)}. & \end{aligned} \quad (38)$$

Denote by $\| K \|_{HS}$ the Hilbert-Schmidt norm of the operator K . Thus

$$\| K \|_{HS}^2 = \sum_{j=1}^{\infty} \| K f_j \|^2,$$

where (f_j) is an orthonormal basis of L^2 .

By Burkholder's inequality, for arbitrary adapted operator valued process ϕ and $p \geq 2$,

$$\begin{aligned} E(\sup_{0 \leq t \leq T} \left| \int_0^t \phi(s) dW(s) \right|^p) & \\ \leq \left(\frac{p}{p-1} \right)^p E \left(\int_0^T \| \phi(s) \|_{HS}^2 ds \right)^{\frac{p}{2}}. & \end{aligned}$$

Therefore

$$\begin{aligned}
E \quad \| Y \|_{L^p([0,T],L^2)}^p &= \int_0^T E \| Y(t) \|^p dt \\
&\leq \left(\frac{p}{p-1}\right)^p \left| \frac{\sin \pi \gamma}{\gamma} \right|^p \\
&\int_0^T [E \left(\int_0^t \| e^{A(t-s)}(t-s)^{-\gamma} [g(v(s)) - g(\bar{v}(s))] \|_{HS}^2 ds \right)^{\frac{p}{2}}] dt.
\end{aligned}$$

Note that

$$\begin{aligned}
&\| e^{A(t-s)}(t-s)^{-\gamma} [g(v(s)) - g(\bar{v}(s))] \|_{HS}^2 \\
&= (t-s)^{-2\gamma} \| e^{A(t-s)} [g(v(s)) - g(\bar{v}(s))] \|_{HS}^2,
\end{aligned}$$

and, for an orthonormal basis (f_j) in L^2 ,

$$\begin{aligned}
&\| e^{A(t-s)} [g(v(s)) - g(\bar{v}(s))] \|_{HS}^2 \\
&= \sum_{j=1}^{\infty} \| e^{A(t-s)} [g(v(s)) - g(\bar{v}(s))] f_j \|^2 \\
&= \sum_{j=1}^{\infty} \sum_{k=1}^{\infty} e^{-2\frac{\pi^2}{\nu} k^2(t-s)} ((g(v(s)) - g(\bar{v}(s))) f_j, e_k)^2 \\
&= \sum_{k=1}^{\infty} e^{-\frac{\pi^2}{\nu} k^2(t-s)} \| (g(v(s)) - g(\bar{v}(s))) e_k \|^2.
\end{aligned}$$

Moreover

$$\begin{aligned}
&\| (g(v(s)) - g(\bar{v}(s))) e_k \|^2 \\
&= \int_0^1 | (g(v(s, x)) - g(\bar{v}(s, x))) e_k(x) |^2 dx \\
&\leq \frac{2}{\pi} \| g \|_{Lip}^2 \int_0^1 | v(s, x) - \bar{v}(s, x) |^2 dx \\
&\leq \frac{2}{\pi} \| g \|_{Lip}^2 \| v(s) - \bar{v}(s) \|^2
\end{aligned}$$

and

$$\begin{aligned}
&\| e^{A(t-s)} [g(v(s)) - g(\bar{v}(s))] \|_{HS}^2 \\
&\leq \frac{2}{\pi} \| g \|_{Lip}^2 \| v(s) - \bar{v}(s) \|^2 \left(\sum_{k=1}^{\infty} e^{-2\frac{\pi^2}{\nu} k^2(t-s)} \right).
\end{aligned}$$

Consequently

$$\begin{aligned} \int_0^T E \| Y(t) \|^p dt & \leq \left(\frac{p}{p-1}\right)^p \left| \frac{\sin \pi \gamma}{\gamma} \right|^p \\ & \int_0^T [E(\int_0^t (t-s)^{-2\gamma} \frac{2}{\pi} \| g \|_{Lip}^2 \| v(s) - \bar{v}(s) \|^2 (\sum_{k=1}^{\infty} e^{-2\frac{\pi^2}{\nu} k^2 (t-s)}) ds)^{\frac{p}{2}}] dt. \end{aligned}$$

But

$$\int_0^t (t-s)^{-2\gamma} (\sum_{k=1}^{\infty} e^{-2\frac{\pi^2}{\nu} k^2 (t-s)}) ds \leq \int_0^{+\infty} s^{-2\gamma} (\sum_{k=1}^{\infty} e^{-2\frac{\pi^2}{\nu} k^2 s}) ds = a_\gamma.$$

Since $\gamma < \frac{1}{4}$, therefore $a_\gamma < +\infty$. Consequently

$$\begin{aligned} \| G(U, v) - G(\bar{U}, \bar{v}) \|_{2,T}^p & \leq T \left(\frac{p}{p-1}\right)^p \left| \frac{\sin \pi \gamma}{\gamma} \right|^p \left(\frac{2}{\pi}\right)^{\frac{p}{2}} \| g \|_{Lip}^2 (a_\gamma)^{\frac{p}{2}} \\ E(\sup_{s \leq T} \| v(s) - \bar{v}(s) \|^p), & \end{aligned} \quad (39)$$

and we can set

$$C_{T,n}^2 = T^{\frac{1}{p}} \left(\frac{p}{p-1}\right) \left(\frac{\sin \pi \gamma}{\gamma}\right) \left(\frac{2}{\pi}\right)^{\frac{1}{2}} \| g \|_{Lip} (a_\gamma)^{\frac{1}{2}}. \quad (40)$$

Step 3⁰. We shall show that for each $n = 1, 2, \dots$ and $T > 0$ there exists a constant $C_{T,n}^3$ such that for $X = \begin{pmatrix} U \\ v \end{pmatrix}$, $\bar{X} = \begin{pmatrix} \bar{U} \\ \bar{v} \end{pmatrix} \in Z_T^p$:

$$\begin{aligned} & \| H_n(U, v) - H_n(\bar{U}, \bar{v}) \|_{2,T} \\ & \leq C_{T,n}^3 \| \begin{pmatrix} U \\ v \end{pmatrix} - \begin{pmatrix} \bar{U} \\ \bar{v} \end{pmatrix} \|_T. \end{aligned} \quad (41)$$

Let us recall that

$$H_n(U, v)(t) - H_n(\bar{U}, \bar{v}) = \int_0^t S(t-s) \left(\frac{\partial}{\partial x} [(\pi_{n,2} v(s))^2] - \frac{\partial}{\partial x} [(\pi_{n,2} \bar{v}(s))^2] \right) ds.$$

By Proposition 11, (see also Lemma 2.1 in [11]), there exists a constant C such that for all $t \in [0, T]$

$$\begin{aligned} & \int_0^t \left\| S(t-s) \frac{\partial}{\partial x} [(\pi_{n,2}v(s))^2 - (\pi_{n,2}\bar{v}(s))^2] \right\| ds \\ & \leq Ct^{\frac{1}{4}} \sup_{s \leq T} \left\| (\pi_{n,2}v(s))^2 - (\pi_{n,2}\bar{v}(s))^2 \right\|_{L^1(0,1)}. \end{aligned} \quad (42)$$

Since

$$\| \pi_n a - \pi_n b \| \leq \| a - b \|, \quad a, b \in L^2,$$

for every $s \in [0, T]$,

$$\| (\pi_{n,2}v(s))^2 - (\pi_{n,2}\bar{v}(s))^2 \|_{L^1(0,1)} \leq 2n \| v(s) - \bar{v}(s) \|.$$

Consequently

$$\begin{aligned} \sup_{t \leq T} \| H_n(U, v) - H(\bar{U}, \bar{v}) \| & \leq 2CnT^{1/4} \sup_{t \leq T} \| v(t) - \bar{v}(t) \|, \\ \| H_n(U, v) - H(\bar{U}, \bar{v}) \|_{2,T} & \leq 2CnT^{\frac{1}{4}} \| v - \bar{v} \|_{2,T}. \end{aligned} \quad (43)$$

We can set

$$C_{T,n}^3 = 2CnT^{1/4}. \quad (44)$$

Step 4⁰. We shall find a constant $C_{T,n}^4$ such that:

$$\begin{aligned} & \| I_n(U, v) - I_n(\bar{U}, \bar{v}) \|_{2,T} \\ & \leq C_{T,n}^4 \left\| \begin{pmatrix} U \\ v \end{pmatrix} - \begin{pmatrix} \bar{U} \\ \bar{v} \end{pmatrix} \right\|_T. \end{aligned} \quad (45)$$

Since $\| S(t) \| \leq 1$ for every $t \geq 0$,

$$\begin{aligned} & \| I_n(U, v)(t) - I_n(\bar{U}, \bar{v})(t) \| \\ & \leq \int_0^t \| S(t-s) \| \left\| \pi_{n,1}U(s) \pi_{n,2}v(s) - \pi_{n,1}\bar{U}(s) \pi_{n,2}\bar{v}(s) \right\| ds \\ & \leq \int_0^t \left\| \pi_{n,1}U(s) \pi_{n,2}v(s) - \pi_{n,1}\bar{U}(s) \pi_{n,2}\bar{v}(s) \right\| ds. \end{aligned}$$

But notice that for all $s \geq 0$

$$\begin{aligned}
& \| \pi_{n,1}U(s) \pi_{n,2}v(s) - \pi_{n,1}\bar{U}(s)\pi_{n,2}\bar{v}(s) \| \\
& \leq \| (\pi_{n,1}U(s) - \pi_{n,1}\bar{U}(s))\pi_{n,2}v(s) \| \\
+ & \| \pi_{n,1}\bar{U}(s)(\pi_{n,2}v(s) - \pi_{n,2}\bar{v}(s)) \| \\
& \leq | \pi_{n,1}U(s) - \pi_{n,1}\bar{U}(s) | \| \pi_{n,2}\bar{v}(s) \| \\
+ & | \pi_{n,1}\bar{U}(s) | \| \pi_{n,2}v(s) - \pi_{n,2}\bar{v}(s) \| \\
& \leq n | U(s) - \bar{U}(s) | + n \| v(s) - \bar{v}(s) \|.
\end{aligned}$$

By the Hölder inequality

$$\begin{aligned}
& \| I_n(U, v) - I_n(\bar{U}, \bar{v}) \|_{2,T}^p \\
& \leq E(\sup_{t \leq T} [n \int_0^t (|U(s) - \bar{U}(s)| + \|v(s) - \bar{v}(s)\|) ds]^p) \\
& \leq n^p E(\int_0^T (|U(s) - \bar{U}(s)| + \|v(s) - \bar{v}(s)\|)^p ds) (\int_0^T ds)^{\frac{p}{q}}.
\end{aligned}$$

Since, for non-negative a, b , $(a+b)^p \leq 2^{p-1}(a^p + b^p)$, we have

$$\begin{aligned}
& \| I_n(U, v)(t) - I_n(\bar{U}, \bar{v}) \|_{2,T}^p \\
& \leq 2^{p-1} n^p T^{p-1} \{ E(\int_0^T (|U(s) - \bar{U}(s)|^p) ds) \\
& + E(\int_0^T (\|v(s) - \bar{v}(s)\|^p) ds) \} \\
& \leq 2^{p-1} n^p T^{p-1} \{ TE (\sup_{s \leq T} |U(s) - \bar{U}(s)|^p) \\
& + TE (\sup_{s \leq T} \|v(s) - \bar{v}(s)\|^p) \}
\end{aligned}$$

However $(a+b)^\alpha \leq a^\alpha + b^\alpha$ for $a, b \geq 0$, $0 < \alpha \leq 1$, and therefore

$$\begin{aligned}
& \| I_n(U, v)(t) - I_n(\bar{U}, \bar{v}) \|_{2,T} \\
& \leq Tn2^{\frac{p-1}{p}} (\|U - \bar{U}\|_{1,T}^p + \|v - \bar{v}\|_{2,T}^p)^{\frac{1}{p}} \\
& \leq Tn2^{\frac{p-1}{p}} (\|U - \bar{U}\|_{1,T} + \|v - \bar{v}\|_{2,T}) \\
& \leq Tn2^{\frac{p-1}{p}} \|X - \bar{X}\|_T.
\end{aligned}$$

And we can set

$$C_{T,n}^4 = Tn2^{\frac{p-1}{p}}. \quad (46)$$

Step 5⁰. Finally set

$$C_{T,n} = \max (C_{T,n}^i, i = 1, 2, 3, 4), \quad (47)$$

then (33) holds.

Taking into account explicit expressions for the constants $C_{T,n}^i, i = 1, 2, 3, 4$, there exists such T_n that $C_{T_n,n} < 1$.

Step 6⁰. By Banach fixed point theorem there exists a unique fixed point of the operator $\begin{pmatrix} U \\ v \end{pmatrix} \rightarrow \begin{pmatrix} F_n(U, v) \\ G(U, v) + H_n(U, v) + I_n(U, v) \end{pmatrix}$ in the space $Z_{T_n}^p$.

Hence there exists a unique solution $\begin{pmatrix} U_n \\ v_n \end{pmatrix}$ of problem (24)-(25). By a standard iteration procedure there exists a unique solution to problem (24)-(25) on arbitrary time interval $[0, T]$. ■

4 Proof of Theorem 3

Let $X_n(t) = \begin{pmatrix} U_n(t) \\ v_n(t) \end{pmatrix}, t \geq 0$, be the solution to problem (11)-(13). Define

$$\tau_n = \min [\inf\{t \geq 0 : |U_n(t)|^2 \geq n^2\}, \inf\{t \geq 0 : \|v_n(t)\|^2 \geq n^2\}]. \quad (48)$$

Notice that $X_n(t) = X_m(t)$ for $m \geq n$ and $t \leq \tau_n$. Therefore, we can set $X(t) = X_n(t)$ if $t \leq \tau_n$ and this is a solution to problem (11)-(13) on the time interval $[0, \tau_\infty)$, where

$$\tau_\infty = \lim_{n \rightarrow \infty} \tau_n.$$

We shall prove that $\tau_\infty = +\infty$.

Let $X(t) = \begin{pmatrix} U(t) \\ v(t) \end{pmatrix}$ be a possibly exploding solution to problem (11)-(13) defined on $[0, \tau_\infty)$. We set

$$V(t) = v(t) - Z(t), \quad (49)$$

that is,

$$\begin{pmatrix} U(t) \\ V(t) \end{pmatrix} = \begin{pmatrix} U(t) \\ v(t) \end{pmatrix} - \begin{pmatrix} 0 \\ Z(t) \end{pmatrix},$$

where

$$Z(t) = \int_0^t e^{A(t-s)} g(v(s)) \chi_{s < \tau_\infty} dW(s), \quad Z(0) = 0.$$

Recall that by the Sobolev imbedding theorem (see [1], Theorem 7.57, p. 217) we have for a domain $\Omega \subset \mathbb{R}^n$ with smooth boundary that if

$$s > 0, 1 < p < n, n > sp \text{ and } p \leq r \leq np/(n - sp), \quad (50)$$

then $W^{s,p}(\Omega)$ is continuously imbedded into $L^r(\Omega)$:

$$W^{s,p}(\Omega) \hookrightarrow L^r(\Omega).$$

Therefore, if $n = 1$, $\Omega = (0, 1)$, $p = 2$, $s = \frac{1}{4}$ and $r = 4$ then (50) holds and

$$H^{\frac{1}{4}}(0, 1) \hookrightarrow L^4(\Omega),$$

where we use notation $W^{s,2}(0, 1) = H^s(0, 1)$. Notice that $H^{\frac{1}{4}}(0, 1) \hookrightarrow L^4(\Omega)$ means that there exists $c > 0$ such that for all $u \in H^{\frac{1}{4}}(0, 1)$

$$\| u \|_{L^4} \leq \| u \|_{H^{\frac{1}{4}}(0,1)}.$$

Moreover, there exists $c > 0$ such that

$$c \| (-\frac{d^2}{dx^2})^{\frac{1}{8}} u \| \geq \| u \|_{H^{\frac{1}{4}}(0,1)}.$$

The following Proposition can be obtained by factorization procedure (see [26], [13] and [17]).

Proposition 5 *Let A be a self-adjoint non-positive operator generating the semigroup $S(t)$, $t \geq 0$, on a Hilbert space H such that*

$$\int_0^T \| S(t) \|_{HS}^2 dt < \infty.$$

Let $0 \leq \gamma + \frac{1}{p} < \frac{1}{2}$ and ξ is an adapted stochastic process with values in the space $L(H) = L(H, H)$ of linear operators in H . Then there exists a constant $C > 0$ such that

$$\begin{aligned} E(\sup_{0 \leq t \leq T} \| (-A)^\gamma \int_0^t S(t-s) \xi(s) dW(s) \|^p) \\ \leq CE(\int_0^T \| \xi(s) \|_{L(H,H)}^p ds). \end{aligned}$$

Applying Proposition 5 with $\gamma = \frac{1}{8}$, $p = 4$, and $\xi(s)$ the multiplication operator by $g(v(s))\chi_{s < \tau_\infty}$;

$$\begin{aligned} E(\sup_{0 \leq t \leq T} \| (-\frac{d^2}{dx^2})^{\frac{1}{8}} Z(t) \|^4) \\ \leq CE(\int_0^T \| \xi(s) \|_{L(L^2, L^2)}^4 ds) < CT \sup_\sigma |g(\sigma)| < \infty. \end{aligned}$$

Let

$$\mu = \sup_{t \in [0, T]} \| Z(t) \|_{L^4}^4. \quad (51)$$

From Proposition 5 and the above estimates we have

$$\begin{aligned} E\mu &= E(\sup_{t \in [0, T]} \| Z(t) \|_{L^4}^4) \leq CE(\sup_{t \in [0, T]} \| Z(t) \|_{H^{\frac{1}{4}}}^4) \\ &\leq CE(\sup_{t \in [0, T]} \| (-\frac{d^2}{dx^2})^{\frac{1}{8}} Z(t) \|^4) < \infty. \end{aligned}$$

Thus

$$E\mu < \infty.$$

The following is a standard result on interpolation inequalities ([22], Corollary 1.1.8).

Corollary 6 *Let $(X, Y)_{\theta, p}$ and $(X, Y)_p$ be interpolation spaces for $0 < \theta < 1$, $1 \leq p \leq \infty$. There is $C(\theta, p)$ such that*

$$\| y \|_{(X, Y)_{\theta, p}} \leq C(\theta, p) \| y \|_X^{1-\theta} \| y \|_Y^\theta \text{ for every } y \in Y.$$

Then, see [22] (Example 1.1.3, pp. 13-14) we get that there exists a constant c such that for $u \in H^1(0, 1)$ and $0 < \theta < 1$

$$\| u \|_{H^\theta(0, 1)} \leq c \| u \|^{1-\theta} \| u \|_{H^1(0, 1)}^\theta. \quad (52)$$

We shall prove the following basic estimate.

Lemma 7 *There exist a constant C such that for arbitrary $\alpha > 0$ and $V \in H_0^1$, $Z \in L^4$ we have*

$$| \int V Z \frac{\partial V}{\partial x} dx | \leq C \| V \|_{L^4}^{\frac{3}{4}} \| V \|_{H_0^1}^{\frac{5}{4}} \| Z \|_{L^4} \quad (53)$$

and

$$\begin{aligned} &\| V \|_{L^4}^{\frac{3}{4}} \| V \|_{H_0^1}^{\frac{5}{4}} \| Z \|_{L^4} \\ &\leq \frac{1}{4} \| V \|^2 \| Z \|_{L^4}^4 + \frac{5}{8} \alpha^2 \| V \|_{H_0^1}^2 + \frac{1}{8\alpha^2} \| V \|^2. \end{aligned} \quad (54)$$

Proof. Observe that from the Schwartz inequality we have

$$\begin{aligned} & \left| \int VZ \frac{\partial V}{\partial x} dx \right| \leq \left(\int V^4 dx \right)^{\frac{1}{4}} \left(\int Z^4 dx \right)^{\frac{1}{4}} \left(\int \left\| \frac{\partial V}{\partial x} \right\|^2 dx \right)^{\frac{1}{2}} \\ & = \|V\|_{L^4} \|Z\|_{L^4} \|V\|_{H_0^1}. \end{aligned}$$

From the Sobolev imbedding inequality we get

$$\|V\|_{L^4} \leq c_1 \|V\|_{H^{\frac{1}{4}}}$$

and from (52) we obtain

$$\|V\|_{H^{\frac{1}{4}}} \leq c_2 \|V\|^{\frac{3}{4}} \|V\|_{H_0^1}^{\frac{1}{4}}.$$

Since $V \in H_0^1$

$$\|V\|_{L^4} \leq c_3 \|V\|^{\frac{3}{4}} \|V\|_{H_0^1}^{\frac{1}{4}}.$$

Therefore there exists c_4 such that

$$\begin{aligned} & \left| \int VZ \frac{\partial V}{\partial x} dx \right| \leq c_4 \|V\|^{\frac{3}{4}} \|V\|_{H_0^1}^{\frac{1}{4}} \|Z\|_{L^4} \|V\|_{H_0^1} \\ & \leq c_4 \|V\|^{\frac{3}{4}} \|V\|_{H_0^1}^{\frac{5}{4}} \|Z\|_{L^4} \end{aligned} \quad (55)$$

and (53) holds.

To prove (54) we observe that using the generalized Young inequality for $\frac{1}{p} + \frac{1}{q} + \frac{1}{r} = 1$, $p, q, r > 0$, with $p = 4$, $q = \frac{8}{5}$, $r = 8$, we get

$$\begin{aligned} & \|V\|^{\frac{3}{4}} \|V\|_{H_0^1}^{\frac{5}{4}} \|Z\|_{L^4} \\ & = \|Z\|_{L^4} \|V\|^{\frac{2}{4}} \|\alpha V\|_{H_0^1}^{\frac{5}{4}} \left\| \frac{1}{\alpha} V \right\|^{\frac{1}{4}} \\ & \leq \frac{\|Z\|_{L^4}^4 \|V\|^2}{4} + \frac{(\|\alpha V\|_{H_0^1}^{\frac{5}{4}})^q}{q} + \frac{(\|\frac{1}{\alpha} V\|^{\frac{1}{4}})^r}{r} \\ & \leq \frac{1}{4} \|V\|^2 \|Z\|_{L^4}^4 + \frac{5}{8} \alpha^2 \|V\|_{H_0^1}^2 + \frac{1}{8\alpha^2} \|V\|^2. \end{aligned}$$

From (53) and (54) we get

$$\begin{aligned} \frac{1}{C} \left| \int VZ \frac{\partial V}{\partial x} dx \right| & \leq \|V\|^{\frac{3}{4}} \|V\|_{H_0^1}^{\frac{5}{4}} \|Z\|_{L^4} \\ & \leq \frac{1}{4} \|V\|^2 \|Z\|_{L^4}^4 + \frac{5}{8} \alpha^2 \|V\|_{H_0^1}^2 + \frac{1}{8\alpha^2} \|V\|^2. \blacksquare \end{aligned}$$

Now we prove

Proposition 8 *If for $V \in C([0, T], L^2)$, $Z \in L^\infty([0, T], L^4(0, 1))$ and continuous function U*

$$\frac{\partial V}{\partial t} = \nu \frac{\partial^2 V}{\partial x^2} + U(V + Z) - \frac{\partial}{\partial x}(V + Z)^2, \quad (56)$$

$$V(0) = v_0, \quad (57)$$

then there exists a constant C such that for all $t \in [0, T]$,

$$\|V\|^2 + U^2 \leq C(\mu + \|v_0\|^2 + U(0)^2 + 1)e^{(C\mu+1)t}, \quad (58)$$

where μ is given by (51).

Proof. We can assume that V is a strong solution to (56). We have

$$\left(\frac{\partial V}{\partial t}, V\right) = \nu \left(\frac{\partial^2 V}{\partial x^2}, V\right) + U(V + Z, V) - \left(\frac{\partial}{\partial x}(V + Z)^2, V\right)$$

so

$$\begin{aligned} \frac{1}{2} \frac{d}{dt}(V, V) &= -\nu \left(\frac{\partial V}{\partial x}, \frac{\partial V}{\partial x}\right) + U(V, V) + U(Z, V) \\ &\quad - \left(\frac{\partial}{\partial x}(V + Z)^2, V\right) \\ &= -\nu \left(\frac{\partial V}{\partial x}, \frac{\partial V}{\partial x}\right) + U(V, V) + U(Z, V) \\ &\quad + (V^2, \frac{\partial}{\partial x} V) + 2(VZ, \frac{\partial}{\partial x} V) + \\ &\quad (Z^2, \frac{\partial}{\partial x} V). \end{aligned}$$

Since

$$\begin{aligned} (V^2, \frac{\partial}{\partial x} V) &= -\left(\frac{\partial}{\partial x} V^2, V\right) = -2\left(\frac{\partial V}{\partial x} V, V\right) \\ &= -2\left(\frac{\partial V}{\partial x}, V^2\right) \end{aligned}$$

so

$$(V^2, \frac{\partial}{\partial x} V) = 0$$

and we have

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} (V, V) &= -\nu \left(\frac{\partial V}{\partial x}, \frac{\partial V}{\partial x} \right) + U(V, V) + U(V, Z) \\ &\quad + 2(VZ, \frac{\partial}{\partial x} V) + (Z^2, \frac{\partial}{\partial x} V) \end{aligned}$$

or

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \| V \|^2 + \nu \| V \|_{H_0^1}^2 &= U \| V \|^2 + U(V, Z) \\ &\quad + 2 \int VZ \frac{\partial V}{\partial x} dx + \int Z^2 \frac{\partial V}{\partial x} dx. \end{aligned}$$

Further we have

$$\begin{aligned} | (Z^2, \frac{\partial}{\partial x} V) | &= | \int_0^1 Z^2(x) \frac{\partial V}{\partial x}(x) dx | \\ &\leq \left(\int_0^1 Z^4(x) dx \right)^{\frac{1}{2}} \| \frac{\partial}{\partial x} V \| \\ &\leq \| Z \|_{L^4}^2 \| \frac{\partial}{\partial x} V \| = \| Z \|_{L^4}^2 \| V \|_{H_0^1} \\ &\leq \frac{\varepsilon}{2} \| V \|_{H_0^1}^2 + \frac{1}{2\varepsilon} \| Z \|_{L^4}^4. \end{aligned}$$

But from (53) and (54) we have

$$\begin{aligned} | \int VZ \frac{\partial}{\partial x} V dx | \\ \leq C \left[\frac{1}{4} \| V \|^2 \| Z \|_{L^4}^4 + \frac{5}{8} \alpha^2 \| V \|_{H_0^1}^2 + \frac{1}{8\alpha^2} \| V \|^2 \right]. \end{aligned}$$

Therefore

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \| V \|^2 + \nu \| V \|_{H_0^1}^2 &\leq U \| V \|^2 + U(V, Z) \tag{59} \\ + 2 \{ C \left[\frac{1}{4} \| V \|^2 \| Z \|_{L^4}^4 + \frac{5}{8} \alpha^2 \| V \|_{H_0^1}^2 + \frac{1}{8\alpha^2} \| V \|^2 \right] \} \\ + \frac{\varepsilon}{2} \| V \|_{H_0^1}^2 + \frac{1}{2\varepsilon} \| Z \|_{L^4}^4. \end{aligned}$$

Now we consider equation

$$\frac{1}{2} \frac{d}{dt} U^2 + \nu U^2 = U(P - \| V + Z \|^2). \tag{60}$$

Adding (59) and (60) we obtain

$$\begin{aligned}
& \frac{1}{2} \frac{d}{dt} [\| V \|^2 + U^2] + \nu \| V \|_{H_0^1}^2 + \nu U^2 \\
& \leq U \| V \|^2 + U(V, Z) + 2C \left[\frac{1}{4} \| V \|^2 \| Z \|_{L^4}^4 + \frac{5}{8} \alpha^2 \| V \|_{H_0^1}^2 + \frac{1}{8\alpha^2} \| V \|^2 \right] \\
& + \frac{\varepsilon}{2} \| V \|_{H_0^1}^2 + \frac{1}{2\varepsilon} \| Z \|_{L^4}^4 + U(P - \| V + Z \|^2) \\
& \leq -U(V, Z) + 2C \left[\frac{1}{4} \| V \|^2 \| Z \|_{L^4}^4 + \frac{5}{8} \alpha^2 \| V \|_{H_0^1}^2 + \frac{1}{8\alpha^2} \| V \|^2 \right] \\
& + \frac{\varepsilon}{2} \| V \|_{H_0^1}^2 + \frac{1}{2\varepsilon} \| Z \|_{L^4}^4 + UP - U \| Z \|^2
\end{aligned}$$

because

$$\begin{aligned}
& U(P - \| V + Z \|^2) \\
& = U(P - \| V \|^2 - 2(V, Z) - \| Z \|^2) \\
& = UP - U \| V \|^2 - 2U(V, Z) - U \| Z \|^2 .
\end{aligned}$$

Observe that from the Young inequality

$$\begin{aligned}
& -U(V, Z) + UP - U \| Z \|^2 \\
& \leq | (V, ZU) | + \frac{U^2}{2} + \frac{1}{2} P^2 + \frac{U^2}{2} + \frac{1}{2} \| Z \|_{L^4}^2 \\
& \leq \| V \| \| U \| \| Z \| + \frac{U^2}{2} + \frac{1}{2} P^2 + \frac{U^2}{2} + \frac{1}{2} \| Z \|_{L^4}^2 \\
& \leq \frac{1}{2} \| V \|^2 + \frac{1}{2} U^2 \| Z \|^2 + \frac{U^2}{2} + \frac{1}{2} P^2 + \frac{U^2}{2} + \frac{1}{2} \| Z \|_{L^4}^2 .
\end{aligned}$$

Thus

$$\begin{aligned}
& \frac{1}{2} \frac{d}{dt} [\| V \|^2 + U^2] + \nu \| V \|_{H_0^1}^2 + \nu U^2 \\
& \leq \frac{1}{2} \| V \|^2 + \frac{1}{2} U^2 \| Z \|^2 \\
& + \frac{U^2}{2} + \frac{1}{2} P^2 + \frac{U^2}{2} + \frac{1}{2} \| Z \|_{L^4}^2 \\
& + 2C \left\{ \frac{1}{4} \| V \|^2 \| Z \|_{L^4}^4 + \frac{5}{8} \alpha^2 \| V \|_{H_0^1}^2 \right. \\
& \left. + \frac{1}{8\alpha^2} \| V \|^2 \right\} + \frac{\varepsilon}{2} \| V \|_{H_0^1}^2 + \frac{1}{2\varepsilon} \| Z \|_{L^4}^4 .
\end{aligned}$$

Now we choose α and ε to get

$$\nu = \frac{\varepsilon}{2} + \frac{5}{8} \cdot 2C\alpha^2.$$

Therefore

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} [\| V \|^2 + U^2] + \nu U^2 \\ & \leq \frac{1}{2} \| V \|^2 + \frac{1}{2} U^2 \| Z \|^2 \\ & + \frac{U^2}{2} + \frac{1}{2} P^2 + \frac{U^2}{2} + \frac{1}{2} \| Z \|_{L^4}^2 \\ & + 2C \left\{ \frac{1}{4} \| V \|^2 \| Z \|_{L^4}^4 + \frac{1}{8\alpha^2} \| V \|^2 \right\} + \frac{1}{2\varepsilon} \| Z \|^4. \end{aligned}$$

For arbitrary $Z \in L^4$,

$$\| Z \| \leq \| Z \|_{L^4}, \quad \| Z \|_{L^4}^2 \leq \| Z \|_{L^4}^4 + 1,$$

therefore, neglecting the term νU^2 in the left hand side of the inequality, we arrive at

$$\begin{aligned} & \frac{d}{dt} [\| V \|^2 + U^2] \\ & \leq C(\| V \|^2 + U^2)(\| Z \|_{L^4}^4 + 1) + C(\| Z \|_{L^4}^4 + 1), \end{aligned}$$

where C is the maximal number among:

$$\frac{C}{2}, \frac{1}{2} + \frac{1}{8\alpha^2}, \frac{3}{2}, \frac{1}{2} P^2 + \frac{1}{2}, \frac{1}{2\varepsilon} + \frac{1}{2}.$$

Consequently

$$\begin{aligned} & \| V(t) \|^2 + U^2(t) \\ & \leq e^{\int_0^t C(\| Z \|_{L^4}^4 + 1) ds} (\| v_0 \|^2 + U^2(0)) + C \int_0^t e^{2 \int_s^t (\| Z(\sigma) \|_{L^4}^4 + 1) d\sigma} (\| Z(s) \|_{L^4}^4 + 1) ds \end{aligned}$$

So the required estimate holds. ■

Continuation of the proof of Theorem 3

Let $X_n(t) = \begin{pmatrix} U_n(t) \\ v_n(t) \end{pmatrix}$ be a, possibly exploding, solution to problem (11)-(13), where $U_n(t)$ is the solution to (18) and $v_n(t)$ is the solution to (19).

By (58) (compare Lemma 3.1 of [11]) there exists a constant $C_1 \geq 1$ such that

$$\begin{aligned} & |U_n(t)|^2 + \|v_n(t)\|^2 + 1 \\ & \leq C_1(\mu + |U_n(0)|^2 + \|v_0\|^2 + 1)e^{(C\mu+1)t} + 1 \\ & \leq C_1(\mu + |U_n(0)|^2 + \|v_0\|^2 + 2)e^{(C\mu+1)t} \end{aligned}$$

so

$$\begin{aligned} & \log(|U_n(t)|^2 + \|v_n(t)\|^2 + 1) \\ & \leq \log C_1 + \log(\mu + |U_n(0)|^2 + \|v_0\|^2 + 2) \\ & \quad + C(\mu + 1)T \end{aligned}$$

so

$$\begin{aligned} & E[\log \sup_{t \leq T} (|U_n(t)|^2 + \|v_n(t)\|^2 + 1)] \\ & \leq \log C_1 + \log(E\mu + |U_n(0)|^2 + \|v_0\|^2 + 2) \\ & \quad + C(E\mu + 1)T. \end{aligned}$$

By Jensen inequality it follows that

$$\begin{aligned} & E(\sup_{t \in [0, T]} \log(|U_n(t)|^2 + \|v_n(t)\|^2 + 1)) \\ & \leq \log C_1 + \log(E\mu + |U_n(0)|^2 + \|v_0\|^2 + 2) \\ & \quad + C(E\mu + 1)T = K_T. \end{aligned}$$

Since by the Chebyshev inequality

$$\begin{aligned} & P(\tau_n \leq T) \\ & = P(\sup_{t \in [0, T]} \log(|U_n(t)|^2 + \|v_n(t)\|^2 + 1) \geq \log(n+1)) \\ & \leq \frac{E(\sup_{t \in [0, T]} \log(|U_n(t)|^2 + \|v_n(t)\|^2 + 1))}{\log(n+1)} \end{aligned}$$

we get, for a new constant K'_T

$$P(\tau_n \leq T) \leq \frac{K'_T}{\log(n+1)} \rightarrow 0$$

as $n \rightarrow \infty$. Hence $\tau_\infty = \infty$. ■

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Appendix

An estimate for extended heat semigroup

Let us recall that $S(t)$ is the heat semigroup introduced in (16). We prove now

Lemma 1. *The operators $S(t)$, $t > 0$, can be extended linearly in the space of all distributions of the form $\frac{\partial}{\partial x}v$, $v \in L^1(0, 1)$, in a way such that*

$$\| S(t) \frac{\partial}{\partial \xi} v \| \leq \| v \|_{L^1(0,1)} \left(\sum_{k=1}^{\infty} \frac{2\pi}{\sqrt{\nu}} k^2 e^{-2\frac{\pi^2}{\nu} k^2 t} \right)^{1/2}.$$

Proof. Set $\nu = 1$. By Parseval's identity

$$\| S(t)u \|^2 = \sum_{k=1}^{\infty} e^{-2\pi^2 k^2 t} (u, e_k)^2, \quad u \in L^2.$$

Let $v \in L^2$ be an absolutely continuous function such that $\frac{\partial}{\partial \xi} v \in L^2$. Then

$$\| S(t) \frac{\partial}{\partial \xi} v \|^2 = \sum_{k=1}^{\infty} e^{-2\pi^2 k^2 t} \left(\int_0^1 \frac{\partial}{\partial \xi} v(\xi) e_k(\xi) d\xi \right)^2.$$

Integrating by parts

$$\sqrt{\frac{2}{\pi}} \int_0^1 \frac{\partial}{\partial \xi} v(\xi) \sin k\pi\xi d\xi = -\sqrt{\frac{2}{\pi}} k\pi \int_0^1 v(\xi) \cos k\pi\xi d\xi.$$

Therefore

$$\left| \int_0^1 \frac{\partial}{\partial \xi} v(\xi) e_k(\xi) d\xi \right| \leq \sqrt{2\pi k} \int_0^1 |v(\xi)| d\xi$$

and consequently

$$\begin{aligned} \left\| S(t) \frac{\partial}{\partial x} v \right\| &\leq \|v\|_{L^1(0,1)} \\ &\times \left(\sum_{k=1}^{\infty} 2\pi k^2 e^{-2\pi^2 k^2 t} \right)^{1/2}. \end{aligned}$$

Since absolutely continuous function with square integrable derivatives are dense in $L^1(0,1)$ the required extension of S exists. It will be denoted with the same symbol $S(t)$, $t \geq 0$. From this lemma follows. ■

Our aim is to prove in an elementary way the following result from [12].

Proposition 9 *For arbitrary $T > 0$ there exists C such that for $t \leq T$ and for measurable, bounded, $L^1(0,1)$ -valued function $v(s)$, $s \in (0,t)$:*

$$\int_0^t \left\| S(\sigma) \frac{\partial}{\partial \xi} v(\sigma) \right\| d\sigma \leq C t^{1/4} \sup_{s \leq t} \|v(s)\|_{L^1(0,1)}.$$

Proof. Set $\nu = 1$. We have to show that for a constant $C > 0$ and $T > 0$

$$\int_0^T \left(\sum_{k=1}^{\infty} e^{-2\pi^2 k^2 t} k^2 \right)^{1/2} dt \leq C T^{1/4}.$$

The function

$$h(t) = \sum_{k=1}^{\infty} e^{-2\pi^2 k^2 t} k^2, \quad t \geq 0$$

is the Laplace transform of purely atomic measure μ which associates with points $2\pi^2 k^2$ masses k^2 , $k = 1, 2, \dots$

Let

$$U(\sigma) = \mu((0, \sigma]) = \sum_{2\pi^2 k^2 \leq \sigma} k^2 = \sum_{k \leq \frac{1}{\pi} \sqrt{\frac{\sigma}{2}}} k^2.$$

One easily finds that U is slowly varying and

$$\lim_{\sigma \rightarrow \infty} \frac{U(\sigma y)}{U(\sigma)} = y^{3/2}, \quad y > 0.$$

Consequently, by tauberian theorems (see [15], p. 422-423)

$$\lim_{t \rightarrow 0} \frac{h(t)}{U(\frac{1}{t})} = \Gamma(\frac{5}{2}).$$

But $U(\frac{1}{t}) \sim \frac{1}{3} \frac{1}{t^{3/2}}$ as $t \rightarrow +\infty$ and therefore

$$h(t) \sim \frac{1}{3\Gamma(\frac{5}{2})} \frac{1}{t^{3/2}}$$

and for a constant C

$$h(t) \leq C \frac{1}{t^{3/2}}, \quad t \leq T_0.$$

Finally

$$\int_0^T h^{1/2}(t) dt \leq C \int_0^T \frac{1}{t^{3/4}} dt = 4CT^{1/4}, \quad T \leq T_0.$$

and therefore, the required inequality follows. ■